# CHERUBINI

# **SPIN WIRE**



	MOTORE TUBOLARE CON REGOLAZIONE MANUALE	
IT	DEL FINECORSA ELETTRONICO PER TENDE TECNICHE E SCREEN	
EN	TUBULAR MOTOR WITH MANUAL ADJUSTMENT OF THE ELECTRONIC LIMIT SWITCH FOR TECHNICAL BLINDS AND SCREENS	
DE	ROHRMOTOR MIT MANUELLER EINSTELLUNG DER ELEKTRONISCHEN ENDLAGEN ZU SCREENS	
FR	MOTEUR TUBULAIRE AVEC RÉGLAGE MANUEL DES FINS DE COURSE ÉLECTRONIQUES POUR STORES TECHNIQUES ET SCREENS	
ES	MOTOR TUBULAR CON REGULACIÓN MANUAL DEL FIN DE CARRERA ELECTRONICO PARA CORTINA ENROLLABLE Y SCREEN	
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**INSTRUCTIONS - INSTRUCCIONES** 

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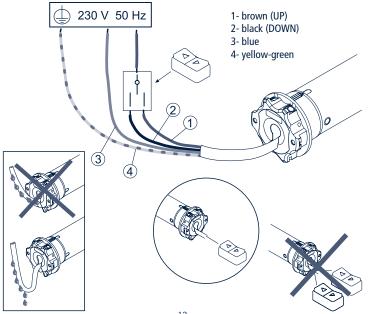
#### **EU DECLARATION OF CONFORMITY**

CHERUBINI S.p.A. declares that the product is in conformity with the relevant Union harmonisation legislation: Directive 2014/35/EU Directive 2014/30/EU Directive 2011/65/EU The full text of the EU declaration of conformity is available upon request at the following website: www.cherubini.it.

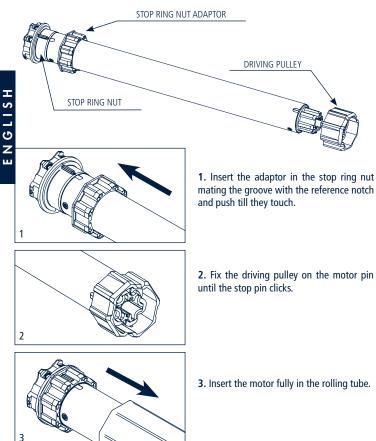
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### **ELECTRICAL CONNECTIONS**

- To prevent any danger or malfunction, the size of electrical control components connected to the motor must be compatible with the electrical features of the motor.
- Means for disconnection must be incorporated in the fixed wiring in accordance with the national installation standards.
- The selectors inverting the direction of rotation of the motor must be provided with mechanical interlocking.
- Invert the brown and the black conductor to change the direction of rotation.
- NEVER connect two or more selectors to the same motor.
- For outdoor use, provide the appliance with a supply cord with designation H05RN-F containing at least 2% of carbon.
- Cable length between motor and control-switch maximal 50 m. In case of cable length more than 50 m an interface-relay have to be used.

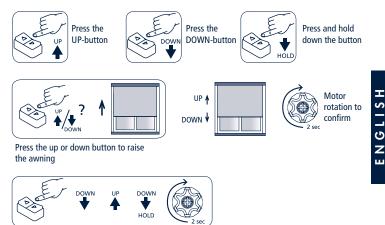


### HOW TO PREPARE THE MOTOR



**NB:** If you use tubes with a round form, the driving pulley must be fixed to the tube, and the installation is to be paid by the person who installs the system. For other tube sections the fitting is optional, but strongly recommended.

### **KEY TO SYMBOLS**



Press the buttons as indicated in rapid sequence and hold the button down at the step marked by "HOLD", to check the motor confirmation movement.

# COMAND SEQUENCES EXAMPLE

Most of the command sequences have three or six distinct steps.

The buttons should be pressed quickly (<0.5 sec) as indicated in the sequence.

The time interval between each step should not be more than 1 second, otherwise the command sequence will be cancelled.

To receive confirmation that the sequence has been accepted by the motor, the button must be held down at the final step marked by HOLD.

Command sequence example in 3 steps:



Attention! If the sequence requires a repetition of the same commands (Up+Up/Down+Down), an interposition of the Stop position could be necessary depending on the type of switch in use.

### LIMIT SWITCH SETTING

The motor can learn the limit switches only in manual mode.

As long as both of the limit switch positions have not been learned, the motor will move briefly, stop and then start back up again.

## PROCEDURE FOR LIMIT SWITCH SETTING

Depending on your individual needs, it's possible to learn first either the upper or the lower limit switch.

#### EXAMPLE 1:

#### SETTING THE UPPER LIMIT SWITCH AS FIRST POSITION

**Z** If the awning is already completely closed up, it must be first opened out to about 20 cm, then proceed as follows.

Using the button switch, bring the awning up to the desired position (for cassetteawnings, hold the button pressed until the motor stops automatically on the closing position).

To set the upper limit switch position perform the indicated sequence of commands (UP-UP-UP) with the button to be linked to the ascent.



Using the button to be linked to descent bring the awning down to the desired position. To set the lower limit switch position perform the indicated sequence of commands (DOWN-DOWN-DOWN).



#### EXAMPLE 2:

#### SETTING THE LOWER LIMIT SWITCH AS FIRST POSITION

#### If the awning is already completely lowered, it must be first raised about 20 cm, then proceed as follows.

Using the button switch, bring the awning down to the desired position.

To set the lower limit switch position perform the indicated sequence of commands, (DOWN-DOWN) with the button to be linked to descent.



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Using the button to be linked to ascent bring the awning up to the desired position (for cassette-awnings, hold the button pressed until the motor stops automatically on the closing position).

To set the upper limit switch position perform the indicated sequence of commands (UP-UP-UP).



### **CHANGING LIMIT SWITCHES**

The following command sequences may be performed only after the limit switches have been set and only when the motor is in one of the two limit switch positions.

### **DELETING OF SINGLE LIMIT SWITCH POSITIONS**

Deleting of the UPPER limit switch.

Take the awning to the upper limit switch and perform the sequence:





Deleting of the LOWER limit switch. Take the awning to the lower limit switch and perform the sequence:



# **DELETING OF ALL LIMIT SWITCH POSITIONS**

From the UPPER position



From the LOWER position



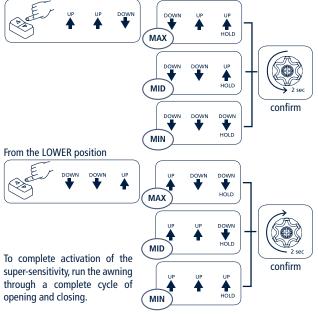
Deleting of one or both limit switches is indicated by the motor pausing briefly before moving again until both limit switch positions have been memorised again.

PLEASE NOTE: When the limit switches are deleted, the super-sensitivity settings are also deleted.

#### ACTIVATION AND ADJUSTMENT OF THE SUPER-SENSITIVITY (only for motors up to 20 Nm)

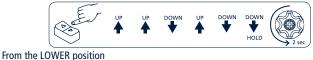
The super-sensitivity feature for obstacles when descending may be enabled on three levels only after both limit switches have been set.

From the UPPER position



#### DEACTIVATION SUPER-SENSITIVITY FUNCTION

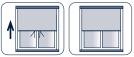
From the UPPER position



### LIMIT SWITCHES AND OBSTACLE DETECTION

#### **Obstacle detection in ASCENT**

Obstacle detection in ascent is enabled only after both the limit switches have been set. In the event of obstacle detection in ascent, the motor will stop without making any movements backwards.



#### **Obstacle detection in DESCENT**

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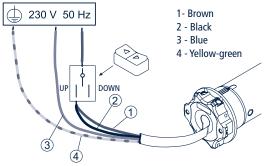
In the event of obstacle detection in descent, with the super-sensitivity feature on, the motor stops and makes a backwards safety movement.



## **RESTORING THE ORIGINAL CONFIGURATION**

#### PLEASE NOTE: recovery of the default configuration will delete the limit switches and disabling the super-sensitivity.

To restore the original motor configuration perform the procedure as described below: - Connect both the brown and black motor wires under the same switch, e.g. UP.



- Press the UP button for at least 2 seconds.
- Disconnect and then restore the original control switch electrical connections (see page 13).

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